Fostering the understanding of sub-footprint heterogeneity in Cosmic-Ray Neutron Sensing, challenges of irrigation monitoring

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Soil moisture (SM) monitoring with cosmic-ray neutron sensors (CRNS)

- To improve irrigation management, help reduce water consumption, and mitigating crop losses, accurate soil moisture (SM) estimation is key.
- Cosmic ray neutron sensors (CRNS) are a promising method in informing irrigation practices due to their large sensed volume (footprint of \sim 130-210 m radius and \sim 15-85 cm depth).

Pilot apple orchard (Agia, Greece)

Sub-footprint heterogeneities are still subject of study and, as a CRNS provides one single estimation of SM over tens of hectares, a small irrigated field (~1-2 ha) is challenging to monitor.

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We tested a novel CRNS correction in a ~1 ha irrigated field and we observed measurements over a 14-ha field irrigated in separate lines.

Pilot potato field (Leerodth, Germany)

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Cosmi Sense

An apple orchard in Agia (Greece) was equipped with 12 SoilNet nodes of SM sensors (at 3 depths), hydrometers four to irrigation, record a compact meteorological station, and a CRNS.



- An additional SM node was installed outside the field to measure SM in the non-irrigated area (Θ_{out}) and thus estimate a synthetic neutron count (N_{out}^{s}) for such area.
- The contribution to the neutron count N of the irrigated area $(\%_{in})$ and of its surroundings ($\%_{out}$) are obtained using neutron transport simulations (URANOS model).
- Four URANOS simulations are sufficient to apply the method



Example of contribution to the count rate of neutrons that originate a) inside the field (45%), b) outside the field (40%), and c) non albedo neutrons (15%)

Starting from measured *N*, calculate:

> Portion of non-albedo neutrons $N_{non-alb} = N/100 * \%_{non-alb}$ Weight of outside-origin neutrons $K_{out} = N_{out}^{s} / 100 * \%_{out}$ $K_{in} = N - K_{out} - N_{non-alb}$ Weight of inside-origin neutrons

- A potato field of 14 ha in Leerodth, was equipped with 3 CRNS from Styx Neutronica GmbH (Germany). Two had one detector tube (P.1 and P.3) and one had two detector tubes (p.2).
- At each CRNS location, two point-scale SM sensors were installed:
 - SoilVUE10 (5, 10, 20, 30, 40, 50 cm depth) from Campbell Scientific Inc. (USA)
 - Drill&Drop (5, 15, 25, 35, 45, 55 cm depth) from Sentek Pty Ltd. (Australia).
- meteorological station was installed at location p.2.
- Electromagnetic induction (EMI) measurements were obtained to select appropriate locations.





- > Synthetic neutron count of the target field
- $N_{in}^{s} = K_{in} * 100 / \%_{in}$



- Estimations from the three CRNS can appear similar during irrigation
- Point-scale SM sensors affected by local effects (e.g., loss of soil contact)
- CRNS may be more suited to estimate a generalized SM value

Advantages and limitations

- CRNS could replace a dense sensor network, which generally is more costly and difficult to manage
- RMSE reduced (0.053 to 0.031) and SM dynamics are improved
- Few overestimations caused by supporting sensor position (too deep)

Conclusions & outlook

- CRNS can monitor and inform irrigation in small irrigated fields (~1 ha) and could sometimes replace a dense sensor network
- CRNS can offer a less site-dependent and more meaningful estimation of SM in certain agricultural contexts
- Further studies are needed to standardize the methodology and test results for different environments and irrigation methods

- Simplified and ad-hoc URANOS simulations provide similar results, and the former could reduce computation effort and increase standardization
- Use a single supporting sensor to correct multiple CRNSS
- Use a second CRNS or other CRNS in the area to perform correction
- Challenging in case of a highly heterogeneous SM distribution

References

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